

# Listing all fixed-length simple cycles in sparse graphs in optimal time

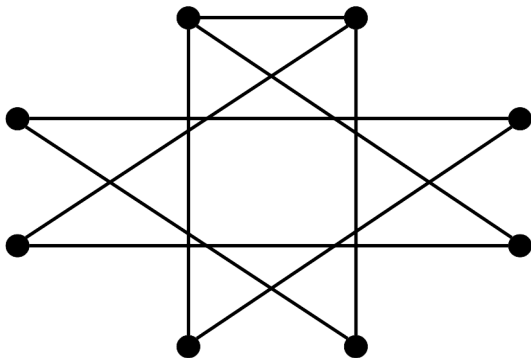
George Manoussakis

Université Paris Saclay, Université Paris Sud, LRI-CNRS, France

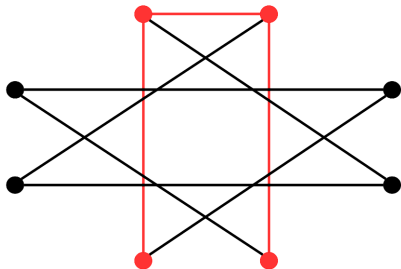
# Introduction

**Input object:** *a graph*

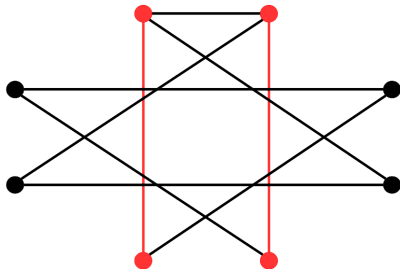
$G = (V, E)$  a graph:  $|V| = n$  vertices and  $|E| = m$  edges.



Question: find all (induced) subgraphs with some property

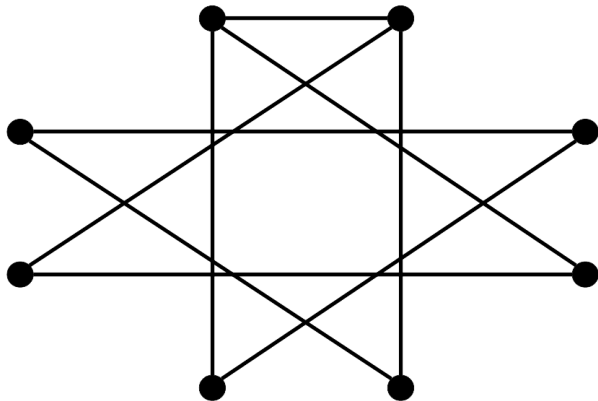


induced subgraph

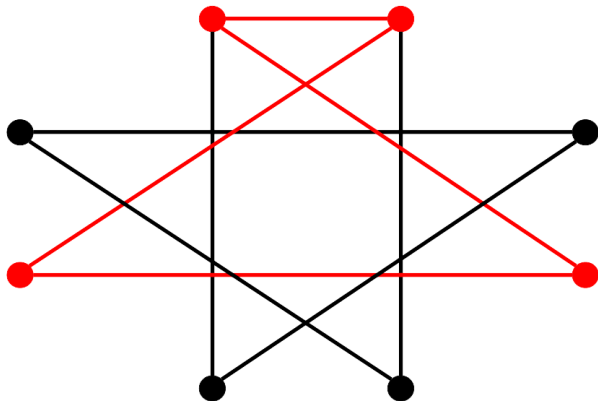


subgraph

**Example:** find all cycles of length four



**Example:** find all cycles of length four



## Definition ( $k$ -degenerate graphs)

Graph  $k$ -degenerate if  $k$  is smallest integer such that:

- every induced subgraph has a vertex of degree at most  $k$ ,  
**or equivalently**

## Definition ( $k$ -degenerate graphs)

Graph  $k$ -degenerate if  $k$  is smallest integer such that:

- every induced subgraph has a vertex of degree at most  $k$ ,  
**or equivalently**
- it has *acyclic orientation* in which every vertex has out-degree bounded by  $k$

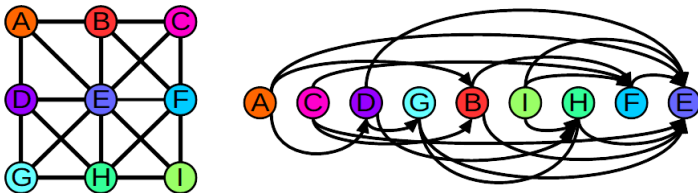
# Introduction - $k$ -degenerate graphs

## Definition ( $k$ -degenerate graphs)

Graph  $k$ -degenerate if  $k$  is smallest integer such that:

- every induced subgraph has a vertex of degree at most  $k$ ,  
**or equivalently**
- it has *acyclic orientation* in which every vertex has out-degree bounded by  $k$

**Example:**



**Figure:** A 3-degenerate graph and a 3-bounded orientation



## Why degenerate graphs

## Why degenerate graphs

- generalize many graphs: planar graphs 5-degenerate, trees 1-degenerate, Barabási-Albert graphs etc.

## Why degenerate graphs

- generalize many graphs: planar graphs 5-degenerate, trees 1-degenerate, Barabási-Albert graphs etc.
- many real world graphs have low degeneracy

Graph	$n$	$m$	$k$
citationCiteseer	268,495	1.1M	15
Flickr	1.72M	15.6M	568
uk-2002	18M	261M	943
Twitter	41.7M	1.20B	2490

## Why degenerate graphs

- generalize many graphs: planar graphs 5-degenerate, trees 1-degenerate, Barabási-Albert graphs etc.
- many real world graphs have low degeneracy

Graph	$n$	$m$	$k$
citationCiteseer	268,495	1.1M	15
Flickr	1.72M	15.6M	568
uk-2002	18M	261M	943
Twitter	41.7M	1.20B	2490

theoretical/practical

**Input:** graph  $G$ ,  $p \in \mathbb{N}$

**Output:** *all cycles subgraphs* of  $G$  with  $p$  vertices (without duplicates)

**Input:** graph  $G$ ,  $p \in \mathbb{N}$

**Output:** *all cycles subgraphs* of  $G$  with  $p$  vertices (without duplicates)

**This talk:**  $\mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$

**Input:** graph  $G$ ,  $p \in \mathbb{N}$

**Output:** *all cycles subgraphs* of  $G$  with  $p$  vertices (without duplicates)

**This talk:**  $\mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$

*worst case output size optimal:*

$\forall k, p$  and  $n \geq kp, \exists$   $n$ -order  $k$ -degenerate graph with  $\Omega(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$   $p$ -cycles.

**Input:** graph  $G$ ,  $p \in \mathbb{N}$

**Output:** *all cycles subgraphs of  $G$  with  $p$  vertices (without duplicates)*

**This talk:**  $\mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$

*worst case output size optimal:*

$\forall k, p$  and  $n \geq kp, \exists$   $n$ -order  $k$ -degenerate graph with  $\Omega(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$   $p$ -cycles.

*space optimal:*

*only requires memory needed to store the graph*



## Related work:

*1 cycle:*

## Related work:

1 cycle:

- $C_3$  in planar graphs in linear time [Papadimitriou *et al.* '81]

## Related work:

1 cycle:

- $C_3$  in planar graphs in linear time [Papadimitriou *et al.* '81]
- $C_3$  and  $C_4$  in planar and degenerate in linear time [Chiba *et al.* '85], [Chrobak *et al.* '91]

## Related work:

1 cycle:

- $C_3$  in planar graphs in linear time [Papadimitriou *et al.* '81]
- $C_3$  and  $C_4$  in planar and degenerate in linear time [Chiba *et al.* '85], [Chrobak *et al.* '91]
- $C_5$  and  $C_6$  in planar in  $\mathcal{O}(n \log n)$  [Richardson *et al.* '86]

## Related work:

1 cycle:

- $C_3$  in planar graphs in linear time [Papadimitriou *et al.* '81]
- $C_3$  and  $C_4$  in planar and degenerate in linear time [Chiba *et al.* '85], [Chrobak *et al.* '91]
- $C_5$  and  $C_6$  in planar in  $\mathcal{O}(n \log n)$  [Richardson *et al.* '86]
- Any length general and degenerate graphs [Alon *et al.* '97]  
for induced cycles : [Cai *et al.* '06]

## Related work:

*all cycles fixed length:*

## Related work:

*all cycles fixed length:*

- any length in planar graphs in  $\mathcal{O}(\text{occurences})$  [Eppstein '95]

## Related work:

*all cycles fixed length:*

- any length in planar graphs in  $\mathcal{O}(\text{occurences})$  [Eppstein '95]
- cycles of length 4 and 5 in degenerate graphs in  $\mathcal{O}(\text{occurences})$  [Kowalik '03]



## Related work:

*all cycles fixed length:*

- any length in planar graphs in  $\mathcal{O}(\text{occurrences})$  [Eppstein '95]
- cycles of length 4 and 5 in degenerate graphs in  $\mathcal{O}(\text{occurrences})$  [Kowalik '03]
- any length in general graphs, randomized in  $\mathcal{O}(f * \text{occurrences})$  with  $f$  time to find one occurrence [Meeks '16].

## Related work:

*all cycles fixed length:*

- any length in planar graphs in  $\mathcal{O}(\text{occurences})$  [Eppstein '95]
- cycles of length 4 and 5 in degenerate graphs in  $\mathcal{O}(\text{occurences})$  [Kowalik '03]
- any length in general graphs, randomized in  $\mathcal{O}(f * \text{occurences})$  with  $f$  time to find one occurence [Meeks '16].

**this talk:** deterministic worst case output size optimal for any length in degenerate graphs in  $\mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$

## Outline of the algorithm: given a $k$ -degenerate graph

- Construct an acyclic orientation of the graph with out-degree bounded by  $k$

## Outline of the algorithm: given a $k$ -degenerate graph

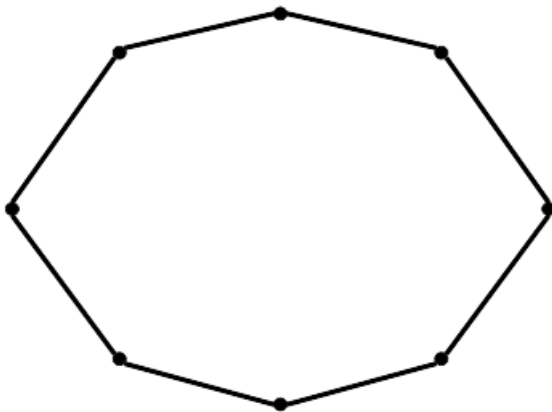
- Construct an acyclic orientation of the graph with out-degree bounded by  $k$
- Prove that any cycle can be decomposed into small easily computable parts

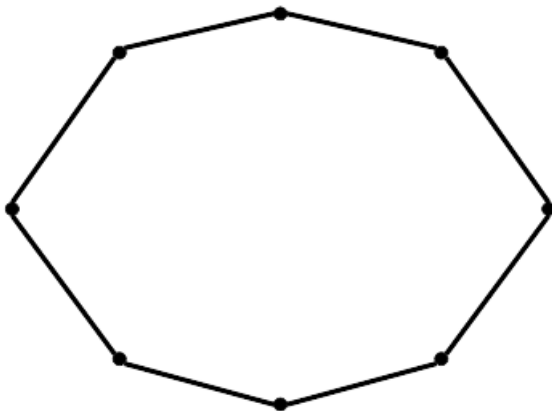
## Outline of the algorithm: given a $k$ -degenerate graph

- Construct an acyclic orientation of the graph with out-degree bounded by  $k$
- Prove that any cycle can be decomposed into small easily computable parts
- Form all possible cycles by computing all these possible parts and their possible combinations

## Outline of the algorithm: given a $k$ -degenerate graph

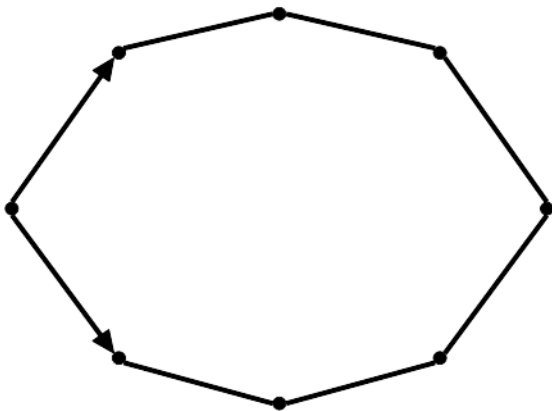
- Construct an acyclic orientation of the graph with out-degree bounded by  $k$
- Prove that any cycle can be decomposed into small easily computable parts
- Form all possible cycles by computing all these possible parts and their possible combinations
- Using properties of the decomposition output each cycle exactly once

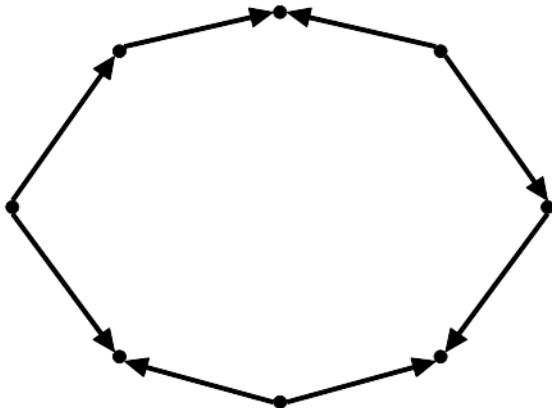


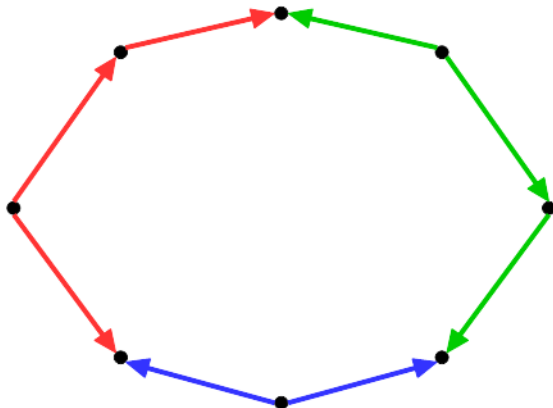


Acyclic orientation:  $\exists$  some vertex with two out-going edges



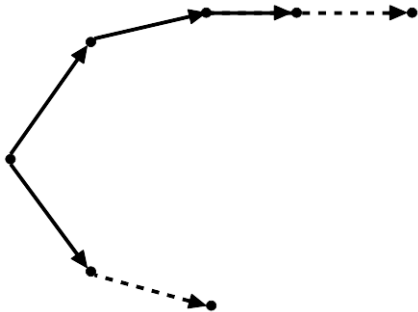






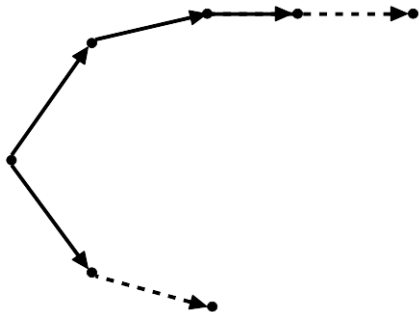
## Definition ( $t$ -path)

$t$ -path of size  $(i, j)$  : two oriented paths of length  $i$  and  $j$  starting from the same vertex



## Definition ( $t$ -path)

$t$ -path of size  $(i, j)$  : two oriented paths of length  $i$  and  $j$  starting from the same vertex



## Remark

in  $k$ -degenerate graphs, at most  $nk^{i+j}$  such paths

**Algorithm: brute force is optimal**

**input:** graph  $G$   $k$ -degenerate

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all possible acyclic orientations of a  $p$ -length simple cycle

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all possible acyclic orientations of a  $p$ -length simple cycle
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$



## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all possible acyclic orientations of a  $p$ -length simple cycle
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$ .

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all possible acyclic orientations of a  $p$ -length simple cycle
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$ .
  4. Construct all possible combinations of these  $t$ -paths in time  $N(|t_1|) * N(|t_2|) * \dots * N(|t_r|)$

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all possible acyclic orientations of a  $p$ -length simple cycle
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$ .
  4. Construct all possible combinations of these  $t$ -paths in time  $N(|t_1|) * N(|t_2|) * \dots * N(|t_r|)$
  5. For each combination: check if it is a cycle + uniqueness

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$
  5. For each combination: check if it is a cycle + uniqueness

Complexity?

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$
  5. For each combination: check if it is a cycle + uniqueness

Complexity?

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$
  5. For each combination: check if it is a cycle + uniqueness

Complexity?

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$   $\mathcal{O}(nk^p)$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$
  5. For each combination: check if it is a cycle + uniqueness

Complexity?

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$   $\mathcal{O}(nk^p)$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$   $\mathcal{O}(n^r k^p)$
  5. For each combination: check if it is a cycle + uniqueness

Complexity?



## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$   $\mathcal{O}(nk^p)$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$   $\mathcal{O}(n^r k^p)$
  5. For each combination: check if it is a cycle + uniqueness  $\mathcal{O}(p)$

Complexity?

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$   $\mathcal{O}(nk^p)$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$   $\mathcal{O}(n^r k^p)$
  5. For each combination: check if it is a cycle + uniqueness  $\mathcal{O}(p)$

**total time:**  $\mathcal{O}(n^r k^p)$

## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$   $\mathcal{O}(nk^p)$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$   $\mathcal{O}(n^r k^p)$
  5. For each combination: check if it is a cycle + uniqueness  $\mathcal{O}(p)$

$$\begin{aligned} & \text{total time: } \mathcal{O}(n^r k^p) \\ & + r \leq \lfloor p/2 \rfloor \implies \mathcal{O}(n^{\lfloor p/2 \rfloor} k^p) \end{aligned}$$

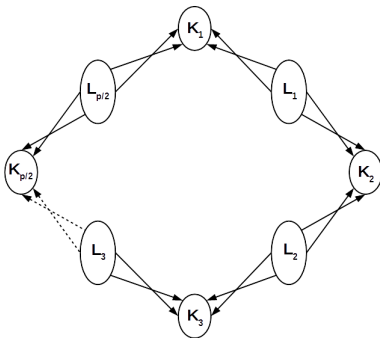
## Algorithm: brute force is optimal

**input:** graph  $G$   $k$ -degenerate

1. Compute all acyclic orientations of a  $p$ -length simple cycle  $\mathcal{O}(2^p)$
2. For each orientation find a  $t$ -path decomposition  $t_1, t_2, \dots, t_r$   $\mathcal{O}(p)$ 
  3. Compute all possible  $t$ -paths of size  $|t_1|, |t_2|, \dots, |t_r|$  in  $G$   $\mathcal{O}(nk^p)$
  4. Construct all possible combinations of these  $t$ -paths in time  $N(t_1) * N(t_2) * \dots * N(t_r)$   $\mathcal{O}(n^r k^p)$
  5. For each combination: check if it is a cycle + uniqueness  $\mathcal{O}(p)$

$$\begin{aligned} & \text{total time: } \mathcal{O}(n^r k^p) \\ & + r \leq \lfloor p/2 \rfloor \implies \mathcal{O}(n^{\lfloor p/2 \rfloor} k^p) \\ & + \text{fine tuning} \implies \mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil}) \end{aligned}$$

## Proof of optimality: (for $k, p$ even)



## Proof of optimality: (for $k, p$ even)

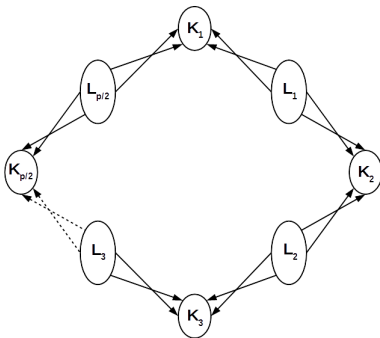


Figure: sets  $K_i$  of size  $k/2$ , sets  $L_i$  of size  $h \geq k$

graph is  $k$ -degenerate

## Proof of optimality: (for $k, p$ even)

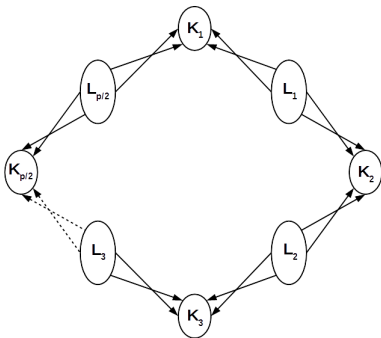


Figure: sets  $K_i$  of size  $k/2$ , sets  $L_i$  of size  $h \geq k$

graph is  $k$ -degenerate

number of vertices:  $n = \frac{p}{2} \frac{k}{2} + h \frac{p}{2} \implies h = \Theta(n)$  if  $n \geq kp$

## Proof of optimality: (for $k, p$ even)

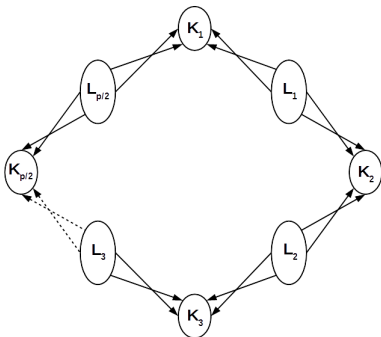


Figure: sets  $K_i$  of size  $k/2$ , sets  $L_i$  of size  $h \geq k$

graph is  $k$ -degenerate

**number of vertices:**  $n = \frac{p}{2} \frac{k}{2} + h \frac{p}{2} \implies h = \Theta(n)$  if  $n \geq kp$

**number of cycles:**  $\left(\frac{k}{2}\right)^{p/2} h^{p/2} = \Omega(k^{p/2} n^{p/2})$



## Open problems:

- List  $p$ -cycles in  $k$ -degenerate graphs in  $\mathcal{O}(\text{occurences})$  ?
- *enumerating*  $p$ -cycles takes time  $\mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil})$   
how much faster is *counting*
  - for general graphs:
    - $\mathcal{O}(n^\omega)$  [Alon *et al.* '97] for cycles length  $\leq 7$
    - $\mathcal{O}(n^{\lceil p/2 \rceil + 3})$  [Vassilevska *et al.* '09]
    - $\mathcal{O}(n^{0.45p + \mathcal{O}(1)})$  [Bjorklund *et al.* '14]
- what if we do not print cycles ?
  - $\mathcal{O}(nk^2)$  for  $C_4$ , [Chiba *et al.* '85]
  - $\mathcal{O}(nk^3)$  for  $C_5$ , [Kowalik '03]
- optimal complexity is attained assuming adjacency matrix, if only adjacency list then  $\mathcal{O}(n^{\lfloor p/2 \rfloor} k^{\lceil p/2 \rceil} \log k)$